**Let’s start with some basic information about NAO:**

### **Key Facts About NAO & Its Manufacturer:**

* **Original Developer:** Aldebaran Robotics (a French company founded in 2005).
* **Acquisition:** In 2015, Aldebaran was acquired by **SoftBank Robotics**, which is headquartered in Japan.
* **Current Manufacturer:** SoftBank Robotics Europe (formerly Aldebaran).
* **Official Website:** SoftBank Robotics
* **Primary Use Cases:** Education, research, healthcare, human-robot interaction, and AI development.

Study NAO [Robot View — Aldebaran 2.1.4.13 documentation](http://doc.aldebaran.com/2-1/software/choregraphe/panels/robot_3d_view.html)

New NAO [NAO AI Edition](https://www.youtube.com/watch?v=8CzDpDWiMEs)

[Aldebaran - Nao6](https://aldebaran.com/nao6/)

**Software downloads**

Choregraphe download [Aldebaran - NAO6 Software downloads](https://aldebaran.com/support/kb/nao6/downloads/nao6-software-downloads/)

Make sure you have Microsoft visual C++ [Download Visual C++ Redistributable Packages for Visual Studio 2013 from Official Microsoft Download Center](https://www.microsoft.com/en-us/download/details.aspx?id=40784)

Python [Python 2.7.0 Release | Python.org](https://www.python.org/download/releases/2.7/)

Python GUI

Study Choregraphe [An Introduction To Robotics With Nao](https://www.kramirez.net/Robotica/Material/Nao/AnIntroductionToRoboticsWithNao_TextBook_2012_US.pdf)

Study Python [Using the API - Making NAO speak — Aldebaran 2.8.7.4 documentation](http://doc.aldebaran.com/2-8/dev/python/making_nao_speak.html)

**Ideas for the projects**

Make NAO sit down